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## IN THE CLAIMS:

Please cancel claims 4-6, 21-22, and 27-57, and amend the claims as follows:

- 1. (Currently Amended) An apparatus for handling a tubular, comprising:
  - a housing for receiving the tubular;
  - a plurality of chambers within the housing;
- a plurality of gripping members disposed in the housing for gripping the tubular, wherein each gripping member moveably mounts to one of the plurality of chambers; and
- a plurality of torque distributors disposed in each of the chambers the housing for engaging the plurality of gripping members, wherein each of the plurality of torque distributors has a contact surface and a load transfer surface, wherein the contact surface is adapted to contact an outer surface of the gripping members and the load transfer surface is adapted to transfer a force from the gripping members to an inner surface of the chamber.
- 2. (Original) The apparatus of claim 1, wherein the plurality of torque distributors prevents the plurality of gripping members from twisting as torque is applied to the tubular.
- 3. (Currently Amended) The apparatus of claim 2, wherein the <u>load transfer</u> surface plurality of torque distributors comprises a pin having an arcuate surface on one side and the contact surface is a flat surface on another.
- 4-6. (Cancelled)
- 7. (Original) The apparatus of claim 1, wherein the plurality of gripping members comprises a piston and cylinder assembly.

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- 8. (Original) The apparatus of claim 7, wherein the piston is attached to the housing and the cylinder is radially movable relative to the piston.
- 9. (Original) The apparatus of claim 7, further comprising an engagement member disposed on the piston and cylinder assembly.
- 10. (Original) The apparatus of claim 9, wherein the engagement member is selected from the group consisting of a jaw, a die, and combinations thereof.
- 11. (Original) The apparatus of claim 7, wherein the plurality of torque distributors prevents the plurality of gripping members from twisting.
- 12. (Original) The apparatus of claim 7, wherein the plurality of torque distributors are disposed parallel to an axis of the piston and cylinder assembly.
- 13. (Original) The apparatus of claim 12, wherein a bending force acting on the piston and cylinder assembly is distributed across the plurality of torque distributors.
- 14. (Original) The apparatus of claim 12, wherein six torque distributors guides each gripping member.
- 15. (Currently Amended) An apparatus for handling a tubular having a first portion and a second portion, comprising:
  - a frame:
  - a first gripping apparatus disposed on the frame;
- a second gripping apparatus disposed on the frame, wherein each of the gripping apparatus includes:
  - a housing for receiving the tubular;
  - a plurality of chambers within the housing
  - a plurality of gripping members disposed in <u>each of the chambers</u> the housing for gripping the tubular; and

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a plurality of torque distributors disposed in the housing for distributing forces acting on the plurality of gripping members, wherein each of the plurality of torque distributors has a contact surface and a load transfer surface, wherein the contact surface is adapted to contact an outer surface of the gripping members and the load transfer surface is adapted to transfer a force from the gripping members to an inner surface of the chamber.

- 16. (Original) The apparatus of claim 15, wherein the first gripping apparatus has torquing capability.
- 17. (Original) The apparatus of claim 15, wherein the second gripping apparatus includes one or more torquing members for rotating the housing.
- 18. (Original) The apparatus of claim 17, wherein the one or more torquing members comprise a piston and cylinder assembly.
- 19. (Original) The apparatus of claim 15, wherein the plurality of torque distributors prevents the plurality of gripping members from twisting.
- 20. (Original) The apparatus of claim 19, wherein each of the <del>plurality of torque</del> distributors <u>load transfer surface</u> has an arcuate surface <del>on one-side</del> and <u>the contact</u> surface has a flat surface <del>on another</del>.
- 21-22. (Cancelled)
- 23. (Original) The apparatus of claim 15, wherein the plurality of gripping members comprises a piston and cylinder assembly.
- 24. (Original) The apparatus of claim 23, further comprising a tubular engagement member disposed on the piston and cylinder assembly.

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- 25. (Original) The apparatus of claim 24, wherein the engagement member is selected from the group consisting of a jaw, a die, and combinations thereof.
- 26. (Original) The apparatus of claim 23, wherein the plurality of torque distributors prevents the plurality of gripping members from twisting.

## 27-57. (Cancelled)

Please add the following new claims:

- 58. (New) The apparatus of claim 1, wherein the inner surface of each of the plurality of chambers have a plurality of recesses adapted to contact the load transfer surface of the plurality torque distributors.
- 59. (New) The apparatus of claim 58, wherein each of the recesses are arcuate.
- 60. (New) The apparatus of claim 15, wherein the inner surface of each of the plurality of chambers have a plurality of recesses adapted to contact the load transfer surface of the plurality torque distributors.
- 61. (New) The apparatus of claim 60, wherein each of the recesses are arcuate.
- 62. (New) The apparatus of claim 15, wherein each of the plurality of gripping members is moveably attached to the housing.
- 63. (New) A method of handling a tubular comprising:
  gripping a tubular in a gripping apparatus, wherein the gripping apparatus

comprises:

a housing;

a plurality of chambers within the housing;

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a plurality of gripping members coupled to the housing, and each gripping member within the one of the chambers;

a plurality of load distributors having a contact surface for engaging the gripping members and a load transfer surface for distributing a load from the gripping member to an inner surface of the chamber;

applying a torque to the tubular with a torquing member couplable to the housing; and

preventing bending of the gripping members by transferring a torque load from the gripping members to the chamber through the load distributors.

- 64. (New) The method of claim 63, further comprising gripping a second tubular in a second housing of a second gripping apparatus.
- 65. (New) The method of claim 64, further comprising coupling the first tubular to the second tubular.
- 66. (New) The method of claim 63, further comprising transferring the torque load to the chamber in a plane substantially parallel to an axis of the gripping member.
- 67. (New) The method of claim 65, further comprising moving the gripping apparatus in a direction substantially parallel to an axis of the first tubular relative to the second gripping apparatus.
- 68. (New) The method of claim 63, further comprising ungripping the tubular.
- 69. (New) The method of claim 68, further comprising removing the tubular from the housing.
- 70. (New) The method of claim 69, further comprising uncoupling one of the plurality of gripping members from the housing.

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- 71. (New) The method of claim 70, further comprising removing the gripping member from the housing creating an empty chamber.
- 72. (New) The method of claim 71, further comprising coupling a new gripping member to the housing in the empty chamber.